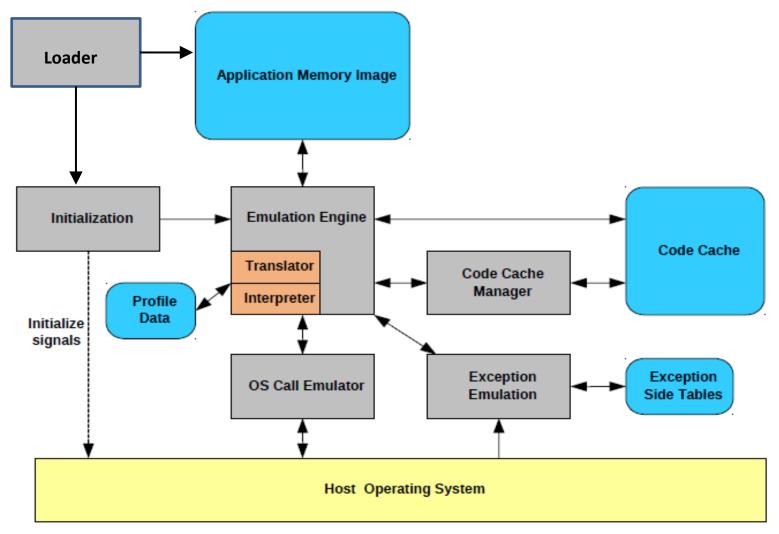
#### **Process Virtual Machines**

## Motivation for Process VMs

- Systems VMs need skill and planning for setup and administration. Useful in large multiorganizational or public cloud setups.
- Process VMs are easy to launch and simple enough to cater to most organizational development and deployment groups.
- Native support for same OS-ISA application base (containers as an example).
- Different OS-ISA combination also easily supported by using emulation and/or binary translation (cygwin?).

#### Process Virtual Machine Implementation Different OS-ISA combination



## Structure of the Process VM

- Loader
  - load guest code and data
  - load runtime code
- Initialization
  - allocate memory
  - establish signal handlers
- Emulation engine
  - interpreter and/or translator
- Code cache manager
  - manage translated guest code
  - flush outdated translations

- Profile database
  - hold program profile info.
  - block/edge/invocation profile
- OS call emulator
  - translate OS calls
  - translate OS responses
- Exception emulator
  - handle signals
  - form precise state
- Side tables
  - structures used during emulation

## **Compatibility Aspects**

- How accurately does the emulation of the guest's functional behaviour compare with its behaviour on its native platform
  - two systems are compatible if, in response to the same sequence of input values, they give the same sequence of output values
- Intrinsic compatibility
  - precise behaviour i.e., behaviour inside VM equivalent to the one on native platform
  - Used and verified while generating the virtualization software
  - difficult to achieve, this method is practically used by hardware designers to ensure ISA compatibility
- Extrinsic compatibility
  - accuracy within some well-defined constraints like specific compiler requirements or logical resources required
    - based on VM implementation, architecture/OS specifications, and external guarantees or certificates
    - some burden on the users to ensure that guarantees are met
  - acceptable for most systems

# Verifying Compatibility

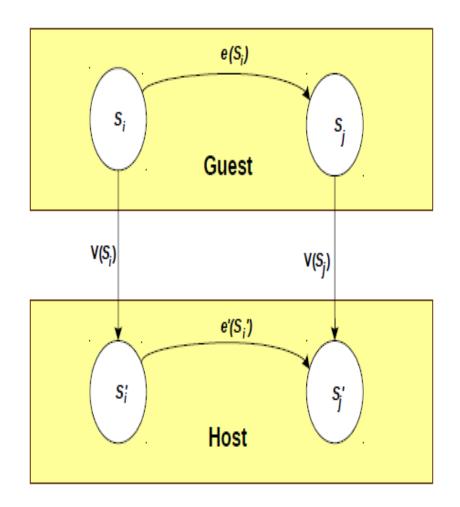
- Too complex to theoretically prove
  - except in simple systems
- In practice
  - use informal reasoning
  - use test suites
- Sufficient conditions
  - decompose compatibility into parts
  - allows the reasoning process to be simplified
- Assume state of guest is 1 to 1 mapped to host
   but same "type" of state is not necessary

## **Compatibility Framework**

- The need for a framework
  - rigorously proving that compatibility holds is hard
  - allow to reason about compatibility issues
  - decide when/where during program execution should compatibility be guaranteed/verified
- Model of program execution
  - machine state, defined by registers, memory, I/O, etc.
  - operations that change state

#### Isomorphism Property

 Isomorphism is having an equal representation or state between the guest and host.

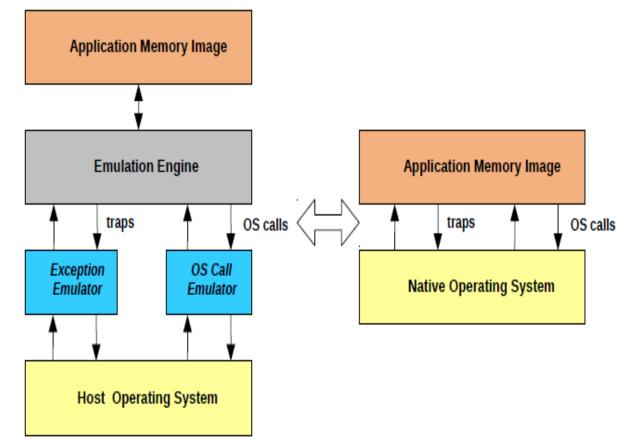


#### **Two-level State Management**

- Managing (changes to) program state at two levels
  - user-managed state
    - main memory, registers
    - straightforward mapping between guest and host states
    - operated on by user-level instructions
  - OS-managed state
    - disk contents, I/O state, networks
    - operated via OS calls, traps, interrupts
    - operations can affect user-level state as well

## **Compatibility Verification**

- Compatibility is only verified at points where control is transferred between the user code and OS
  - establish one-toone mapping between control transfer points
  - in both native platform and VM



## **Compatibility Validation**

- Conditions for compatibility
  - guest state should be equivalent to host state at
    - control transfer from user instructions to OS
    - control transfer from OS to user instructions
  - all user-managed state must be compatible
  - instruction-level equivalence not required

## **Trap Compatibility**

- If source traps, then target traps
  - If target traps, then source would have trapped
  - runtime can filter target traps, to remove false ones
- Page faults are special case
  - page fault behaviour is non-deterministic w.r.t. user process

Source	Target
	• • •
r4 🖸 r6 + 1	R4 🖸 R6 + 1
r1 🛛 r2 + r3 → <i>trap</i>	R1 🛛 R4 + R5 $\rightarrow$ remove dead assignment
r1 🛛 r4 + r5	R6 🛛 R1 * R7
r6 🖸 r1 * r7	

## **Register State Compatibility**

- At the time of an exception is the register state exactly as in the real machine?
  - including dead register values?

```
R1 <- R2 + R3

R9 <- R1 + R5

R6 <- R1 * R7

R6 <- R1 * R7

R7 \rightarrow trap?

R6 <- R1 * R7

R3 <- R6 + 1

R3 <- R6 + 1
```

## Memory State Compatibility

 Memory state compatibility is maintained if, at the time of a trap or interrupt, the contents of memory are exactly the same in the translated target program as in the original source program

```
Source
```

R7 🛛 R6 << 8 A: mem (R6) 🖓 R1 B: mem (R7) 🖓 R2

```
Target
```

```
R7 ☑ R6 << 8
B: mem (R7) ☑ R2
A: mem (R6) ☑ R1→protection fault?
```

## Memory Ordering Compatibility

Maintain equivalent consistency model

Important for multiprocessors

 A=Flag=0;

 P1
 P2

 A = 1;
 while (Flag == 0);

 Flag = 1;
 ... = A;

Good refresher on Memory Consistency Models: www.cs.pdx.edu/~walpole/class/cs510/spring2010/slides/4.ppt

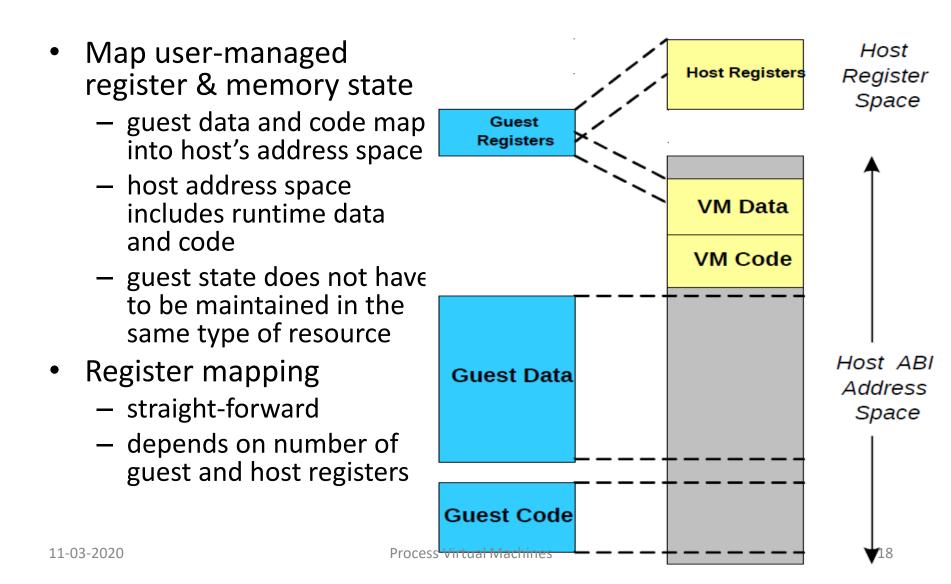
### **Undefined Architecture Cases**

- Some (most?) ISAs have undefined cases
  - example: self-modifying code with I-caches
  - unless special actions are performed, result may be undefined
- Different, undefined behavior is compatible behavior
  - can be tricky
  - what if undefined behavior is different from all existing implementations?
  - what if existing implementations do the "logical" thing?
    - e.g., self-modifying code works as "expected"

## Constructing a Process VM

- Mapping of user-managed state
  - held in registers
  - held in memory
- Perform emulation (operations to transform state)
  - memory architecture emulation
  - instruction emulation
  - exception emulation
  - OS emulation

## State Mapping

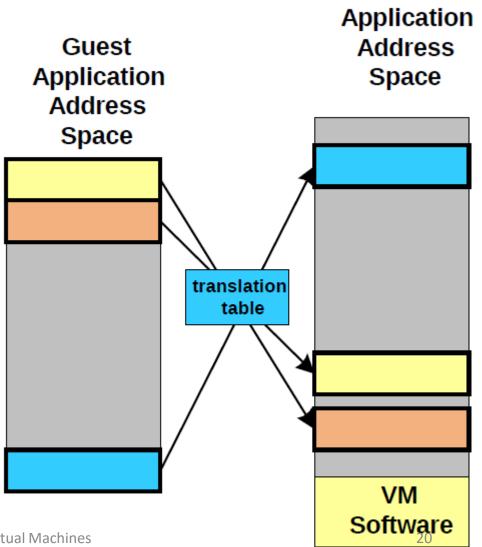


## Memory State Mapping

- Memory address space mapping
  - map guest address space to host address space
  - maintain protection requirements
- Methods results in different performance and flexibility levels
  - software supported translation table
  - direct translation

## Software Translation Tables

- VM software maintains translation table
  - map each guest memory address to host address
  - similar to hardware page tables / TLBs
  - used when all other approaches fail
  - provides most flexibility and least performance



Host

#### **Address Translation Tables**

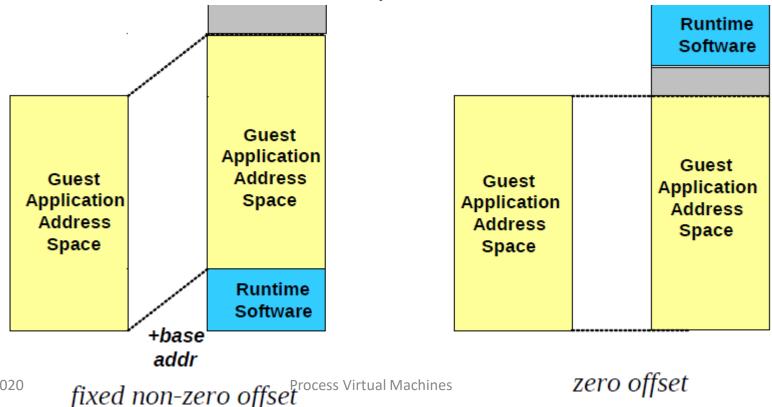
Initially, R1 holds source address R30 holds base address of mapping table

srwi r29,r1,16 slwi r29,r29,2 lwzx r29,r29,r30 slwi r28,r1,16 srwi r28,r28,16 slwi r29,r29,16 or r29,r28,r29 lwz r2,0(r29)

;shift r1 right by 16 ;convert to a byte address ;load block location in host memory ;shift left/right to zero out ;source block number ;shift up target block number ;form address ;do load

### **Direct Memory Translation**

- Use underlying hardware
  - guest memory allocated contiguous host space
  - guest address space + runtime <= host address space</p>
  - minimal overhead, most performance



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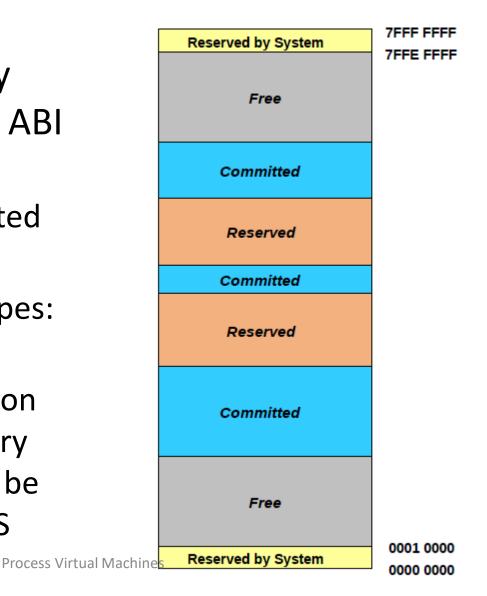
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## Memory Compatibility - Summary

- Runtime + guest space <= host space
  - direct memory translation
  - can achieve performance and intrinsic compatibility
- Runtime + guest space > host space
  - software translation
  - will lose intrinsic compatibility, performance or both
- Guest space == host space
  - happens often, same-ISA dynamic translation
  - no room for runtime
    - use software translation, extrinsic compatibility

## **Memory Architecture Emulation**

- Aspects of memory architecture of the ABI
  - Address space
     structure: segmented
     or flat
  - Access privilege types:
     N, R, W, E
  - Protection/allocation
     granularity: memory
     block size that can be
     allocated by the OS



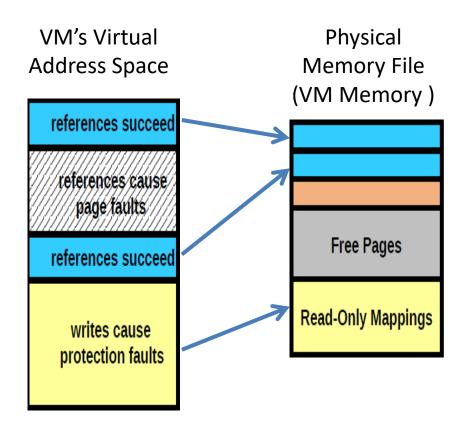
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## **Guest Memory Protection**

- Access restrictions placed on different regions of memory.
- Can be achieved during software supported translation
  - slow and inefficient, but very flexible
- Host supported memory protection
  - runtime sets access restrictions using OS system calls
  - OS delivers signals to runtime on access violations
  - protection faults reported to runtime
  - requires host OS support

## Host OS Support

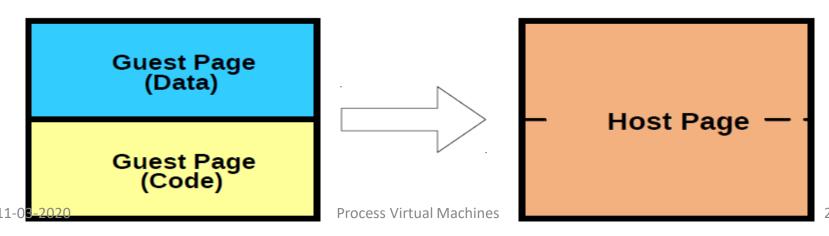
- Direct mechanism
  - runtime sets protection levels via system calls (mprotect)
  - protection faults trap to handler in runtime (SIGSEGV)
- Indirect mechanism
  - mapping region of memory to file with access protections (mmap)



#### Indirect Mechanism

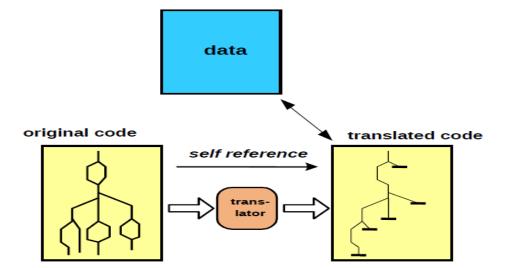
## **Guest Memory Protection**

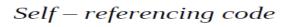
- Implementation issues
  - host and guest ISAs provide different protection types
  - host provides a superset of guest protections
- host provides a subset of guest protections
   host and guest support different page sizes
  - difficult to map access privileges
  - simple if guest page size is a multiple of host page size

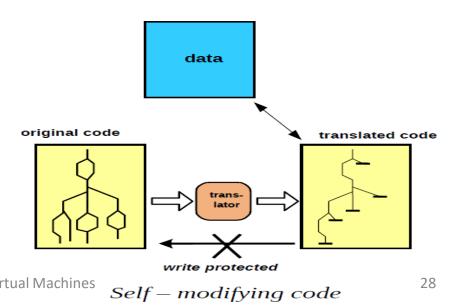


# Self Referencing/Modifying Code

- Program may either refer to itself, or attempt to modify itself.
- Solution
  - maintain guest program code memory image
  - load/store addresses are mapped into source memory region
  - loads from code region are ok
  - writes to code region trigger segmentation fault
    - flush relevant cache entry, enable writes to code region, interpret the code block that caused the fault, re-enable write-protection Process Virtual Machines







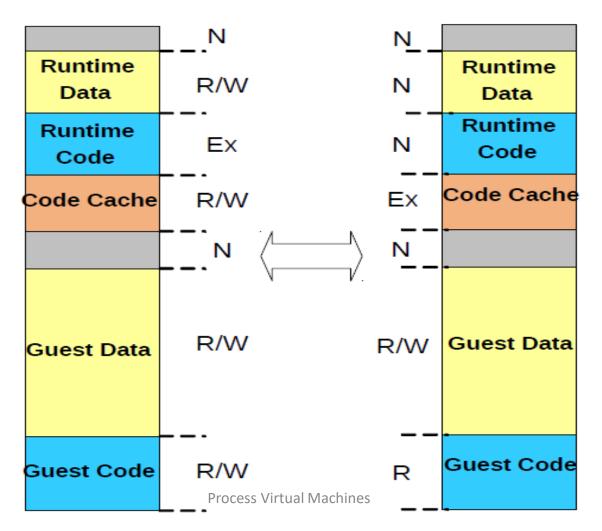
## **Runtime Memory Protection**

- Runtime and guest application share the same process address space
  - guest program can read/write portions of the runtime
- Addressing
  - software translation tables
  - hardware address translation, software protection checking
  - hardware for both address translation and protection checking
    - OS sets protections for *emulation* mode and *runtime* mode
- Change protections on *context switch* from runtime to translated code
- Translated code can only access guest memory image
- Translated code cannot jump outside code cache (emulation s/w sets up links)
- Multiple system calls at context switch time
  - high overhead

### **Memory Mapping for Protection**

Runtime mode

Emulation mode

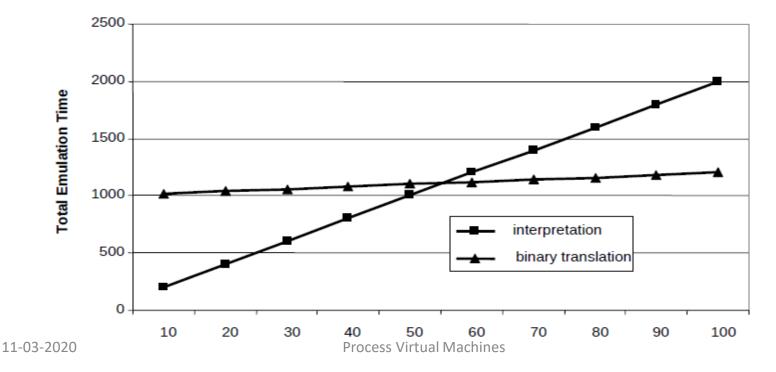


#### Instruction Emulation

- Techniques for instruction emulation
  - interpretation, binary translation
- Start-up time (S)
  - cost of translating code for emulation
  - one time cost for translating code

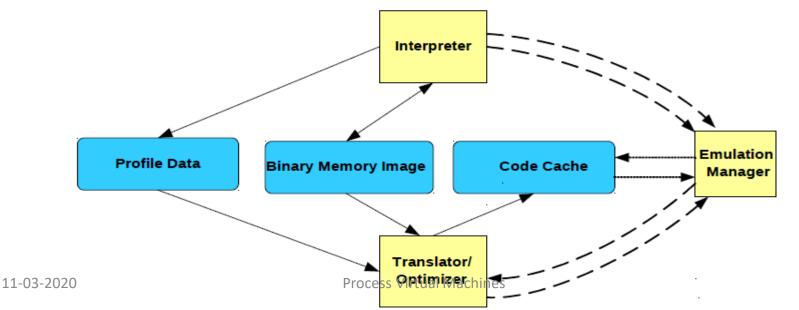
Steady-state performance (T) cost of emulation average rate at which instructions are emulated
Overall performance (S + NT) N is the number of times an instruction is executed

S=1000, T=2/20, tradeoff point=55ins

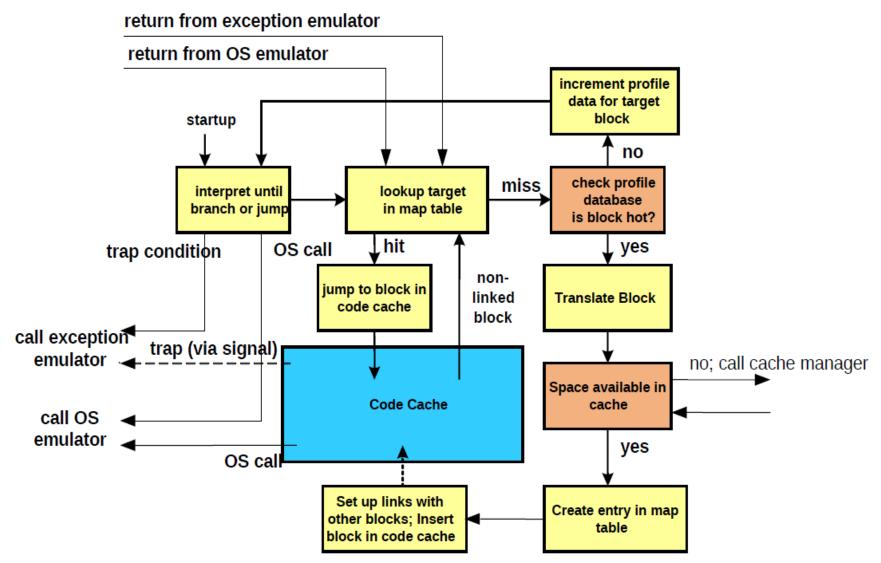


## **Staged Emulation**

- Application of emulation techniques in stages
  - start with low start-up overhead tech. (interpretation)
  - profile data determines hot dynamic blocks of code
  - if execution count > threshold, then compile
  - place in code cache, update links and side table entries
  - optimize *hotter* code further ?



#### **Execution Flow Through Emulation Engine**



### **Exception** emulation

- Types of exceptions
  - *trap*: produced by a specific program instruction during program execution
  - *interrupt*: an external event, not associated with a particular instruction
- Precise exceptions
  - all prior instructions have committed
  - none of the following instructions have committed
- Further division of exceptions for a process VM
  - ABI visible: exceptions returned to the application via an OS signal
  - ABI invisible: ABI is unaware of the exception's occurrence

## Trap detection

- Detecting trap conditions
  - *interpretive trap detection*: checking trap conditions during interpretation routine
  - trap condition detected by the host OS
- Implementation
  - runtime registers all exceptions with the host OS
  - all signals registered by the guest program are recorded
  - on receiving OS signal, if signal is guest-registered then send to guest signal-handling code
  - else, runtime handles the trap condition
  - special tables needed during binary translation

## **Interrupt Handling**

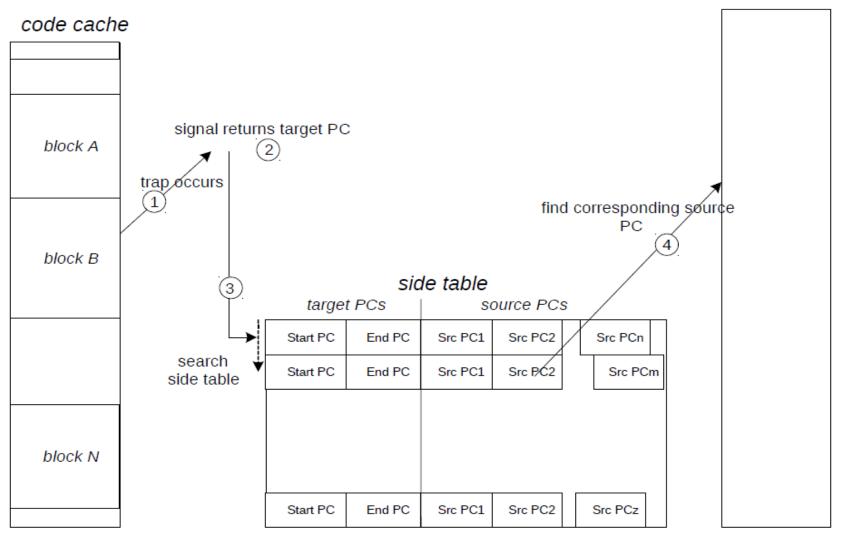
- Interrupts are not associated with any instruction
  - a small response latency is acceptable
  - maintaining precise state easier than traps
- Receiving interrupt during interpretation
  - complete current routine
  - service interrupt
- Receiving interrupt during binary translation
  - execution may not be at an interruptible point
  - precise recovery at arbitrary points difficult
  - no idea when control will return to the emulator from the code cache

# **Determining Precise State**

- Interpreter
  - easy, each source instruction has its own routine
  - source PC and state updated in each instruction routine
- Binary Translation
  - hard, first determine the source PC
  - source PC not continuously updated
  - maintain *reverse translation table* mapping target PC to source PC, inefficient
  - target instruction can map to multiple source instructions
  - target code may be optimized, and re-ordered

### **Reverse Translation Table**

source code



## **Restoring Precise State**

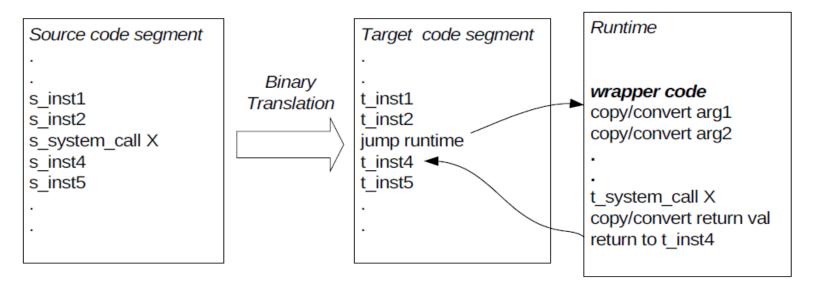
- Register state (during binary translation)
  - 2 cases, based on if source-to-target register mapping remains constant throughout emulation
  - if not constant, side tables can be maintained, or analyzed from start of translation block again
- Memory State (during binary translation)
  - changed by store instructions
  - do not reorder stores, or other potentially trapping instructions with stores
  - restricts optimizations

# **OS Call Emulation**

- Emulates the function or semantics of the guest's OS calls
   not emulate individual instructions in the guest OS
- Different from instruction emulation
  - given enough time, any function can be performed on the input operands to produce a result
  - most ISAs perform same functions, ISA emulation is always possible
  - with OS, it is possible that providing some host function is impossible, operation semantic mismatch
- Different source and target OS
  - semantic translation of mapping required
  - may be difficult or impossible
  - ad-hoc process on a case-by-case basis
- Same source and target OS
  - emulate the guest calling convention
  - guest system call jumps to runtime, which provides wrapper code

#### **OS Call Emulation**

- Same source and target OS (cont...)
  - runtime may handle some guest OS calls itself (signals, memory management)
  - handling abnormal conditions like callbacks, runtime maintaining program control, lack of documentation



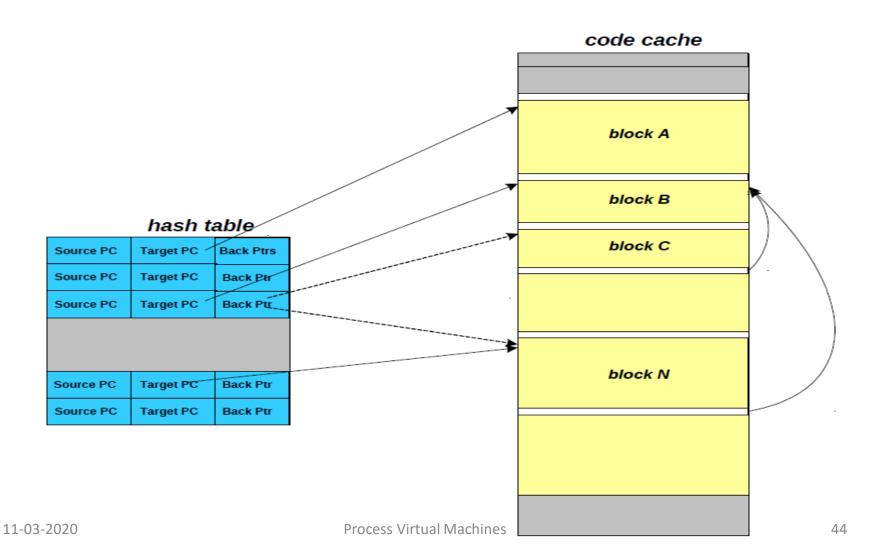
### Code Cache

- Storage space for holding translated guest code.
- Code cache is different from ordinary caches
  - code cache blocks do not have a fixed size
  - code cache blocks are chained with each other
  - code cache blocks are not backed up
  - has implications on code cache management (replacement) algorithms used
- Code cache space is limited
  - blocks need to be replaced if cache fills up

## Code Cache Replacement

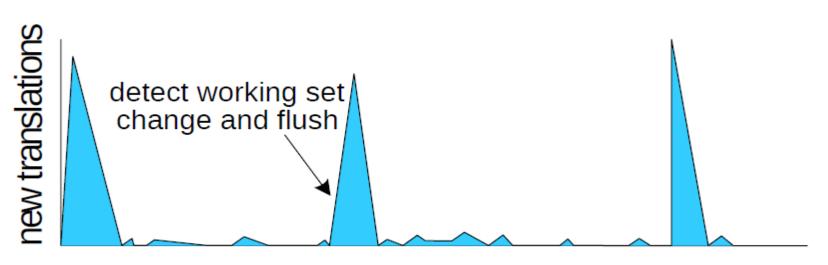
- Least recently used (LRU)
  - good in theory, problematic in practice
  - overhead of keeping track of the LRU block
  - *backpointers* are needed to eliminate chained links
  - fragmentation problem due to variable-sized blocks
  - unlink blocks before removing
    - maintain backpointers

### **Code Cache Backpointers**



#### Code Cache Replacement

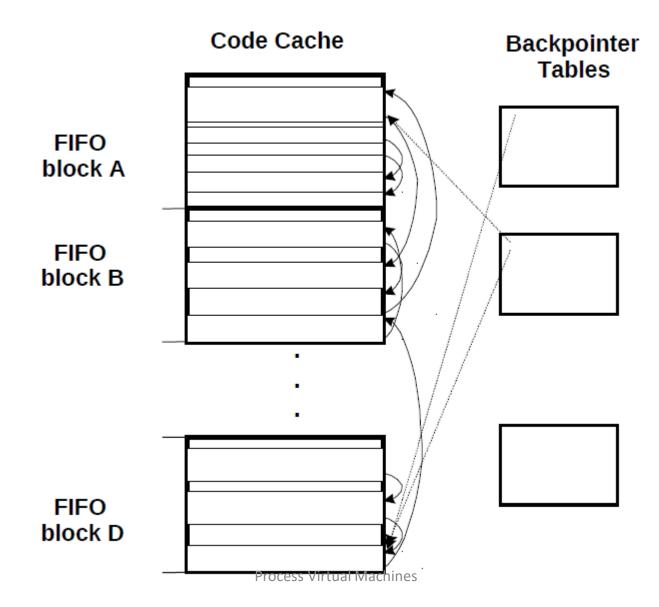
- Cache flush
  - when full or on phase change
  - gets rid of stale blocks
  - minimal maintenance overhead
  - even actively used blocks may be removed, and may need re-translation



## Code Cache Replacement

- First In First Out (FIFO)
  - non-fragmenting, as cache can be maintained as a circular buffer
  - alleviates LRU problems at lower hit rates
  - needs to maintain backpointers
- Course-grained FIFO
  - partition code cache into large FIFO blocks
  - Links only maintained between blocks that span replacement boundaries

### **CCR-** Coarse Grained FIFO



11-03-2020

# Performance of Process VM

- Important for VM acceptance
  - optimization framework along with staged emulation
- Difference from static optimization
  - conservative, over small code regions, traces, superblocks
  - high level semantic information not available
  - profiling, architectural information can be used
- Dynamic Binary Optimization
  - Used mostly in same ISA process VMs to improve on native execution performance.

# Summary

- Process VM implementation using instruction emulation:
  - Interpretation
  - Binary translation
  - Staged interpretation with code caches
- Challenges in implementing Process VMs
  - State management
  - Exception handling
  - Memory address space mapping
  - OS call handling